Small Business Innovation Research/Small Business Tech Transfer

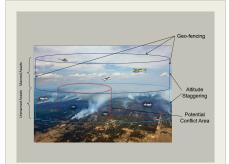
ON-DEMAND: Operations in Dynamic Environments with Manned And Unmanned Aircraft Deconfliction, Phase I



Completed Technology Project (2017 - 2017)

Project Introduction

NASA Unmanned Traffic Management Program (UTM) and its early builds focus on requirements for fixed geofencing and low-altitude UAS without interaction with manned flights. However, later builds will require functionality for operation in dynamic missions employing multiple collaborating UAS in mixed manned-unmanned teams, and in environments where pre-specified geofencing, flight planning, and separation rules are not applicable. To address this challenge, SSCI proposes to develop, implement and test an innovative ON-DEMAND (Operations in Dynamic Environments with Manned And Unmanned Aircraft Deconfliction) system, a portable ATC center, whose role will be to monitor the environment, predict the environmental changes, and approve new geofencing boundaries, new manned-unmanned vehicle separation boundaries, and new flight plans in real-time while avoiding conflicts and assuring overall system safety. Specific system functions will include: (i) Prediction and adjustment of the geofence boundaries based on user requests or environmental changes; (ii) Prediction of the effects of user commands which may generate potential conflicts between manned and unmanned aircraft; and (iii) Dynamic mission re-planning, requiring real-time generation of new flight-plans under separation assurance guidelines. The main project objective is to develop requirements for the design and implementation of a local ATC for dynamically varying environments. We plan to propose an effective mission and flight plan re-planning approach, and effective conflict monitoring and resolution procedures which will enable smooth mission operation while assuring overall system safety. Under the project SSCI will leverage its state-of-the-art flight path prediction routines, collision detection and avoidance system, and system-level safety evaluation approach. Phase I will also include simulation testing and flight data collection with our partners at Olin College of Engineering.



ON-DEMAND: Operations in Dynamic Environments with Manned And Unmanned Aircraft Deconfliction, Phase I Briefing Chart Image

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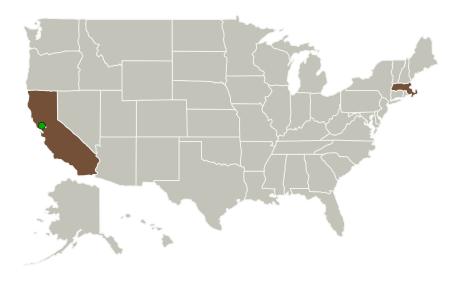


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Primary U.S. Work Locations and Key Partners



Organizations Performing Work	Role	Туре	Location
Scientific Systems Company, Inc.	Lead Organization	Industry Small Disadvantaged Business (SDB)	Woburn, Massachusetts
Ames Research Center(ARC)	Supporting Organization	NASA Center	Moffett Field, California

Primary U.S. Work Locations	
California	Massachusetts

Organizational Responsibility

Responsible Mission Directorate:

Space Technology Mission Directorate (STMD)

Lead Organization:

Scientific Systems Company, Inc.

Responsible Program:

Small Business Innovation Research/Small Business Tech Transfer

Project Management

Program Director:

Jason L Kessler

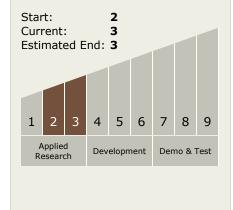
Program Manager:

Carlos Torrez

Principal Investigator:

Joseph Jackson

Technology Maturity (TRL)





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Images



Briefing Chart Image

ON-DEMAND: Operations in Dynamic Environments with Manned And Unmanned Aircraft Deconfliction, Phase I Briefing Chart Image (https://techport.nasa.gov/imag e/128007)

Technology Areas

Primary:

 TX16 Air Traffic Management and Range Tracking Systems
 TX16.1 Safe All Vehicle Access

Target Destinations

The Sun, Earth, The Moon, Mars, Others Inside the Solar System, Outside the Solar System

